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Adaptive robust beamformer for multi-pair two-way relay networks with imperfect channel state information

Key words: Multi-pair two-way relay, Adaptive robust beamformer, Channel state information (CSI), Maximum signal-to-interference-and-noise ratio (Max-SINR), Maximum signal-to-leakage-and-noise ratio (Max-SLNR)

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Motivation

- In wideband multi-pair two-way relay networks, the performance of beamforming at a relay station (RS) is intimately related to the accuracy of the channel state information (CSI) available.
- The accuracy of CSI is determined by Doppler spread, delay between beamforming and channel estimation, and density of pilot symbols, including transmit power of pilot symbols.
- Therefore, we develop an adaptive robust Max-SINR plus Max-SLNR beamformer of tracking the channel variation by taking Doppler spread, delay between channel estimation and beamforming, and the density and power of pilot symbols into account.

Paper contribution

- We design the transmit and receive beamforming matrices at the RS by making use of Max-SINR and Max-SLNR criteria in the presence of imperfect CSI.
- The coefficients of the Gaussian-Markov CSI error model are modeled as a function of CSI delay, Doppler spread, and signal-to-noise ratio, and can be estimated in real time.
- In accordance with the real-time estimated coefficients of the error model, an adaptive robust Max-SINR plus maximum Max-SLNR beamformer at an RS is proposed to track the variation of CSI error.

System model

- One central relay station (RS) with N antennas
- K pairs of mobile stations (MSs) with M antennas

$$\begin{aligned} r_{k_i}^{uq} = & \beta (G_{k_i}^{uq})^T W_{RS}^{uq} H_{k(-i)}^{uq} s_{k(-i)}^{uq} \\ & + \beta (G_{k_i}^{uq})^T W_{RS}^{uq} H_{k_i}^{uq} s_{k_i}^{uq} + c_{k_i}^{uq} \\ & + \beta (G_{k_i}^{uq})^T W_{RS}^{uq} z_{RS}^{uq} + z_{k_i}^{uq}, \end{aligned}$$

CSI error model

$$\widehat{H}_{k_i}^{(u-\Delta u)q} = \rho_H H_{k_i}^{uq} + \sqrt{1 - \rho_H^2} H_{e,k_i}^{uq}$$

$$\widehat{G}_{k_i}^{(u-\Delta u)q} = \rho_G G_{k_i}^{uq} + \sqrt{1 - \rho_G^2} G_{e,k_i}^{uq},$$

Proposed adaptive robust beamformer

$$\mathbf{W}_{\text{RS}}^{uq} = \sum_{k=1}^K \sum_{i \in \{a,b\}} \mathbf{W}_{t,k_i}^{uq} \left(\mathbf{W}_{r,k(-i)}^{uq} \right)^T$$

Max-SLNR

$$B_{k_i} = \frac{\Psi_1}{\sigma_{\text{RS}}^2 \mathbf{I}_N + P_{\text{RS}} N^{-1} (\Psi_2 + \Psi_3)}$$

Max-SINR

$$\mathbf{A}_{k(-i)} = \frac{\Phi_1^T}{\sigma_{\text{RS}}^2 \mathbf{I}_N + P_{\text{MS}} M^{-1} (\Phi_2 + \Phi_3)^T}$$

Real-time estimation of ρ

$$\rho_{H,k_i}^u = \rho_{H,k_i}^{ud} \rho_{H,k_i}^{ue}$$

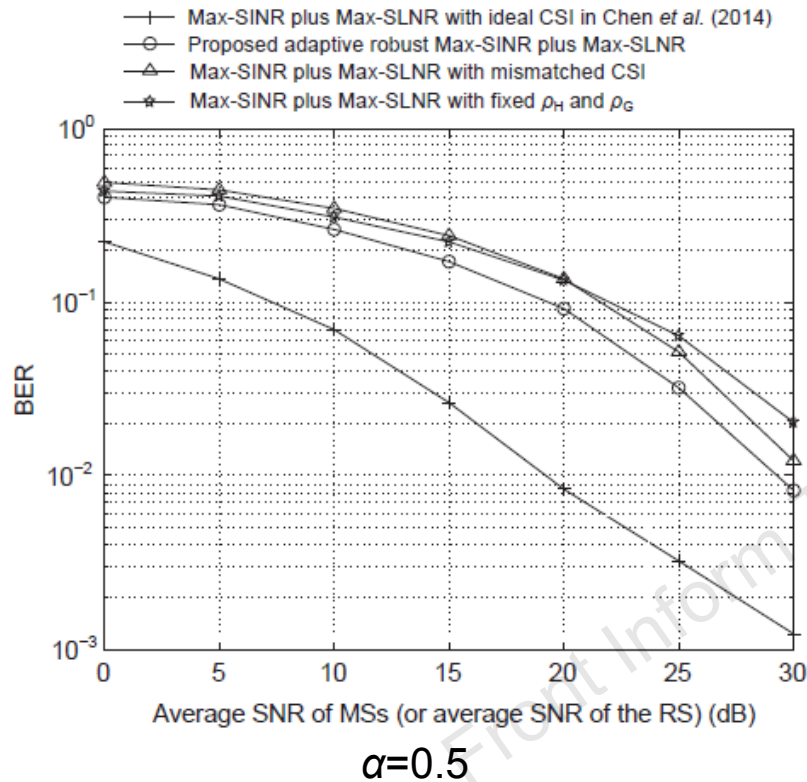
effect of Doppler spread

$$\rho_{H,k_i}^{ud} = \frac{\Re_{HH,k_i}(\Delta u, 0)}{\Re_{HH,k_i}(0, 0)}$$

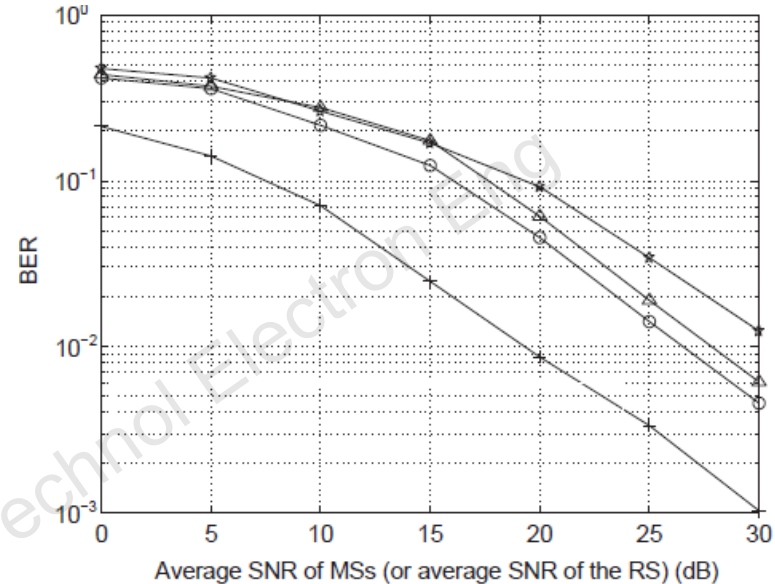
effect of channel estimation error

$$\rho_{H,k_i}^{ue} = \frac{\text{SNR}_{H,k_i}^{up}}{1 + \text{SNR}_{H,k_i}^{up}}$$

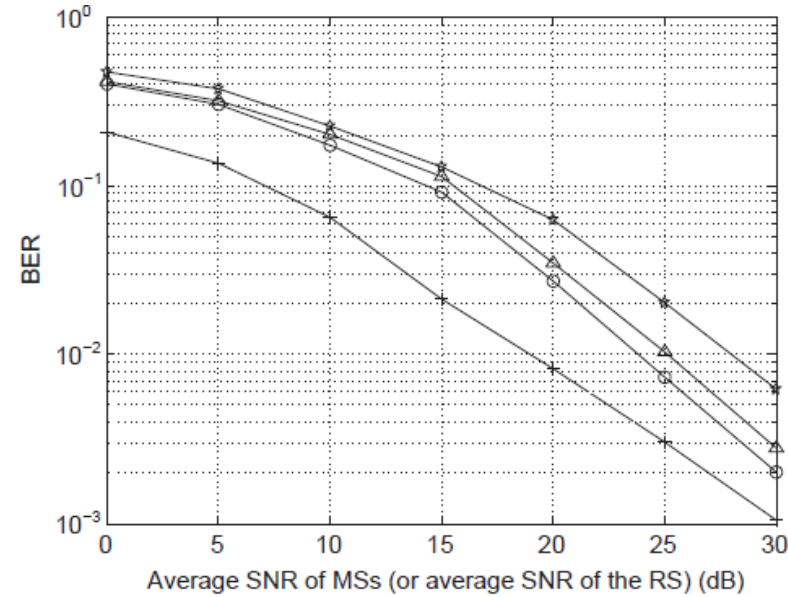
Major results



Curves of BER versus SNR of the proposed adaptive robust beamformer and existing non-adaptive ones ($\Delta m f_d T_s = 0.01$)

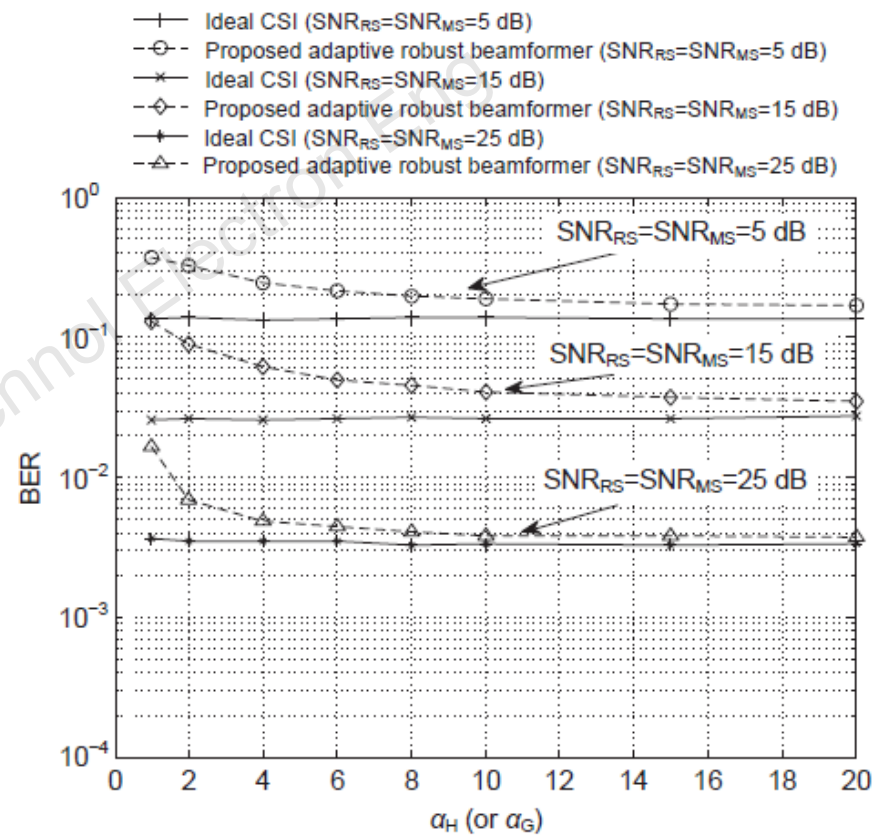
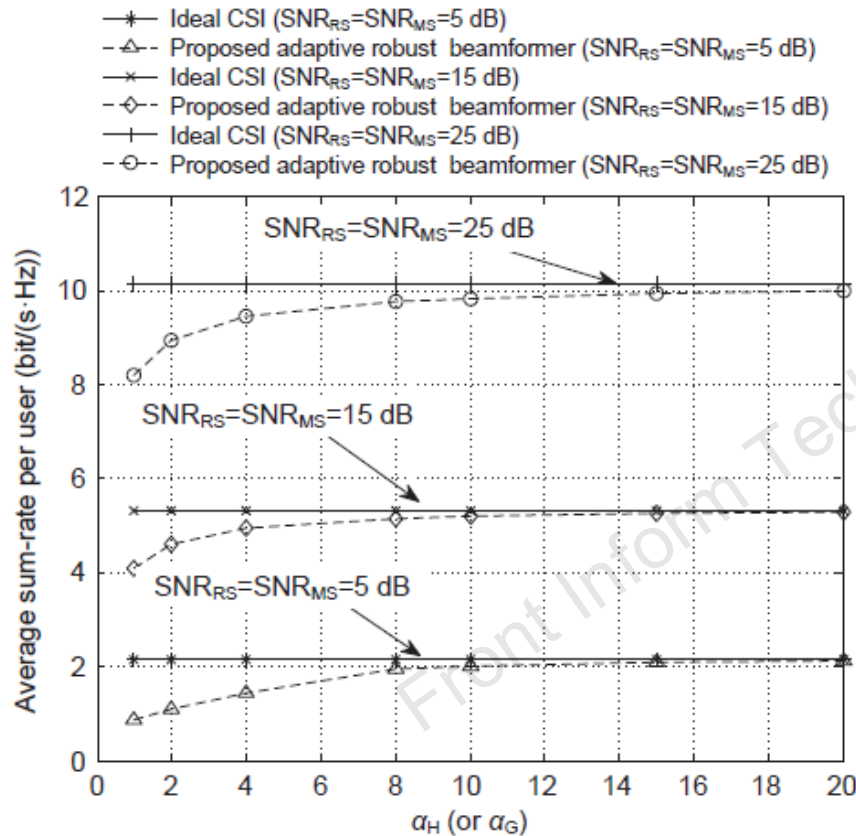


$\alpha=1.0$



$\alpha=2.0$

Major results (Cont'd)



Curves of sum-rate and BER versus α of the proposed adaptive robust beamformer at $\text{SNR}_{\text{RS}}=\text{SNR}_{\text{MS}}=5$ dB, 15 dB, 25 dB ($\Delta m f_d T_s = 0.01$)

Conclusions

- By real-time estimation of Doppler spread and SNR in the channel, an adaptive robust Max-SINR plus Max-SLNR beamformer at an RS is proposed to take into account some uncertainty or possible variation in the channel matrix.
- From simulation results and analysis, we find that the proposed robust method can adaptively track channel variation and performs much better than existing robust and non-robust Max-SINR plus Max-SLNR non-adaptive schemes.