

**Editorial:****Complex systems and networks with their applications**

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Complex systems and networks capture most of the features in existing systems and have gained considerable attention over the past several decades. In recent years, research has extended to the fields of networked control systems, cyber-physical systems, logical networks, neural networks, and related topics. This is mainly due to rapid developments in communication, computer, and information technologies, which enable the handling of large-scale data that cannot be easily handled via traditional methods. More importantly, newly invented technologies such as wireless sensor networks, decentralized control, and deep learning techniques need distributed control strategies to ensure their robustness, flexibility, scalability, low cost, and easy configuration and maintenance.

Recent decades have witnessed massive developments and advances in complex systems and networks. Many insightful results and powerful methods have been reported. Complex systems and networks have been broadly applied to both civil and military fields. Typical examples include transportation systems, power grids, health and medical fields, aerospace, and industrial systems. With increasing demands for clean energy, low cost, more security, and better health, the study of complex systems and networks is attracting more attention, from both aca-

demic and industrial communities.

In this context, the Chinese Academy of Engineering (CAE) organized a special issue of *Frontiers of Information Technology & Electronic Engineering*, focusing on complex systems and networks with their applications. This special issue aims to promote research on complex systems and networks, and to reflect on the most recent advances, with emphasis on both theories and applications. After a rigorous review process, 12 papers by researchers worldwide have been selected for this special issue, including two survey papers and 10 research papers.

Xiao-di LI and his collaborators gave a comprehensive survey of impulsive control strategies, focusing on the field of complex networks. They concentrated on impulsive control and impulsive perturbation, and surveyed several aspects of complex dynamic networks with impulsive effects: synchronizing and desynchronizing impulses, adaptive-impulsive synchronization, pinning impulsive synchronization, and complex dynamical networks with stochastic and impulsive effects. They also suggested some future research directions. Hai-tao LI and his collaborators carried out a detailed survey on new developments in control design techniques of logical control networks, including the reachable set approach, pinning control design, control Lyapunov function approach, and sampled-data control method.

Jin-de CAO and his collaborators discussed the multiple Mittag-Leffler stability problem for fractional-order quaternion-valued neural networks in

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the presence of impulsiveness, due to the wide applications of neural networks. They showed the existence of equilibrium points using a tool derived from the geometrical properties of activation functions when the Lipschitz condition is assured. With the help of the Lyapunov technique, they also examined the condition of the global Mittag-Leffler stability of multiple equilibrium points for impulsive fractional-order quaternion-valued neural networks. The methods developed were carefully verified by numerical examples.

With the rapid developments in logical networks, Wei-hua GUI and his collaborators proposed an output feedback stabilizer design of a Boolean network (BN) based on the network structure. Unlike traditional pinning control designs, their design is not based on the state transition matrix of BNs, and can efficiently determine the pinning control nodes and reduce computational complexity. Their simulations and experiments using a signal transduction network and a *D. melanogaster* segmentation polarity gene network showed good performance and adaptability of the method.

Logical networks as a typical formalism to model genetic regulatory networks has been a hotspot of interest, and found wide applications in fields such as systems biology, power grids, combustion engines, game theory, encryption, and robotics. Since the development of the algebraic state space approach, it has become easier to analyze the structure and dynamics, and to consider the control problems of logical control networks, including Boolean and multi-valued logical networks.

Jian-quan LU and his collaborators reported switching-based stabilization of aperiodic sampled-data Boolean control networks with all subsystems that are unstable. Their method can not only solve the global stability problem of a Boolean control network under aperiodic sampled-data control when all subsystems of the transformed switched network are unstable, but also be adapted for research on the global stability of switched Boolean networks containing all subsystems that are unstable. Compared with research on the global stability of switched Boolean networks with all unstable subsystems, the problem of aperiodic sampled-data with all subsystems that are unstable is more complex.

In recent years, synchronization and consensus phenomena have attracted much attention in attempts to understand how collective behavior emerges in networked systems. Chi HUANG and his collaborators presented a new method on bisimulation-based stabilization of probabilistic Boolean control networks with state feedback control, which can be used to reduce the high computational complexity. A necessary and sufficient condition was put forward based on a powerful matrix manipulation, and the propagation of stabilization with a probability of 1 between bisimilar probabilistic Boolean control networks was considered and demonstrated attainable. Lulu LI and his collaborators investigated the complete synchronization problem of coupled delayed Boolean networks, where the state delays and output delays may not be equal, and the state delay in each Boolean network may be different. One necessary and sufficient condition was proposed for complete synchronization, and a corresponding algorithm was given.

Jin-feng PAN and Min MENG considered optimal one-bit perturbation in Boolean networks based on cascading aggregation, which maximizes the size of basins of attractions of desired attractors and minimizes that of undesired attractors. Based on an aggregation method, a necessary and sufficient condition was given to ensure the invariance of desired attractors after one-bit perturbation. Their experiments on a T-cell receptor network demonstrated the validity, feasibility, and effectiveness of the proposed method.

Cascading decomposition, as an essential and special form of decomposition of Boolean control networks, is a theoretically interesting and practically useful concept. Yi-feng LI and Jian-dong ZHU reported their study of two types of cascading decomposition problems of Boolean control networks using a graph-theoretical method. A new graphic concept called “nested perfect equal vertex partition” was proposed; necessary and sufficient graphic conditions were then obtained. In addition, the logical coordinate transformations were constructively obtained to realize the corresponding cascading decomposition forms. The validity, feasibility, and effectiveness of their proposed method were shown by experimental data.

Because of time-consuming processes involved in DNA transcription and RNA translation, time delay

is inevitable in the gene regulatory process, and plays a key role in the development of living organisms. Recently, several interesting results have been reported from using delayed logical control networks. In this issue, Ya-ting ZHENG and Jun-e FENG described their investigation into the output tracking problem of delayed logical control networks with state and control constraints under transformation into a set stabilization issue. Based on a deformation of the state transition matrix, several necessary and sufficient conditions were derived, and a design of admissible state feedback controllers was proposed. Their experiments demonstrated the validity, feasibility, and effectiveness of the proposed method.

Recently, there have been rapid developments in neural networks encouraged by their potential applications, such as in medical image edge detection, medical event detection, pattern recognition, and robotics. Yang CAO and his collaborators reported their study of inertial bidirectional associative memory neural networks subject to mixed delays and impulsive effects. With the aid of differential inequality techniques, they provided criteria guaranteeing the existence, uniqueness, and global exponential stability of anti-periodic solutions in the considered system. An example was presented to show the efficiency of the results.

Accessibility of traffic information has enormous potential to automotive powertrain control. Ming-xin KANG and Jin-wu GAO described a gearshift control scheme in which the control design gearshift strategy can be formulated within the framework of the logical system. Towards this goal, vehicle dynamics were modeled by a Markov process. The fuel optimization problem was formulated via a receding horizon optimal control problem in the framework of the logical system. A tool from dynamic programming was used to solve the underlying optimal problem. Simulation results were given to support these designs.

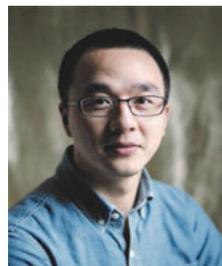
The papers included in this special issue cover a broad spectrum of current research topics on logical networks, complex systems, and neural networks, including stabilization, tracking and decomposition problems of logical networks, analysis and synthesis on neural networks, synchronization problems in

complex networks via impulsiveness-based control strategies, and even the optimization of fuel efficiency of vehicles. We hope that this special issue will benefit researchers in these fields and foster research on complex systems and logical networks, neural networks, and related fields.

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