



Erratum:

Erratum to: Research on the continuous positioning control to servo-pneumatic system

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The original version of this article unfortunately contained a mistake. In the second page, before Fig. 2, Eq. (7) was missing, which is given below:

$$q_m = \begin{cases} \frac{A(u)}{\sqrt{T}} \sqrt{\frac{k-2}{R(k-1)}} p_s \sqrt{\left(\frac{p}{p_s}\right)^{2/k} - \left(\frac{p}{p_s}\right)^{(k+1)/k}}, & \frac{p}{p_s} > C_{r1}, \\ A(u) C_{r2} (p_s - p)^2, & \frac{p}{p_s} \leq C_{r1}. \end{cases} \quad (7)$$